Albert-Ludwigs-Universität Freiburg Lecture: Introduction to Mobile Robotics Summer term 2016 Institut für Informatik

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Sheet 11

Topic: FastSLAM Due date: 08.07.2016

Exercise: FastSLAM Implementation

Implement the landmark-based FastSLAM algorithm as presented in the lecture. Assume known feature correspondences.

To support this task, we provide a detailed listing of the algorithm as a PDF file and a small *Octave* framework (see course website). The framework contains the following folders:

data contains files representing the world definition and sensor readings.

octave contains the FastSLAM framework with stubs to complete.

plots this folder is used to store images.

The below mentioned task should be implemented inside the framework in the directory octave by completing the stubs.

After implementing the missing parts, you can run the FastSLAM system. To do that, change into the directory octave and launch *Octave*. Type fastslam to start the main loop (this may take some time). The script will produce plots of the state of the FastSLAM algorithm and save them in the plots directory. You can use the images for debugging and to generate an animation. For example, you can use ffmpeg from inside the plots directory as follows:

ffmpeg -r 10 -b 500000 -i fastslam_%03d.png fastslam.mp4

Implement the correction step in correction_step.m. For the noise in the sensor model, assume that Q_t is a diagonal 2×2 matrix as follows

$$Q_t = \begin{pmatrix} 0.1 & 0\\ 0 & 0.1 \end{pmatrix}.$$

Some implementation tips:

• Turn off the visualization to speed up the computation by commenting out the line plot_state(... in the file fastslam.m.

- While debugging, run the filter only for a few steps by replacing the for-loop in fastslam.m by something along the lines of for t = 1:50.
- When converting implementations containing for-loops into a vectorized form it often helps to draw the dimensions of the data involved on a sheet of paper.
- Many of the functions in *Octave* can handle matrices and compute values along the rows or columns of a matrix. Some useful functions that support this are sum, cumsum, sqrt, sin, cos, and many others.