Seminar on Robot Navigation

NAME:_________________________________

EMAIL:_________________________________

1. Detection of Principal Directions in Unknown Environments for Autonomous Navigation
2. Asymptotically optimal motion planning for robots with linear dynamics
3. Anytime Safe Interval Path Planning in Dynamic Environments
4. Bearings-only Path Following with a Vision-based Potential Field
5. C2TAM: A Cloud framework for cooperative tracking and mapping
6. Planning most-likely paths from overhead imagery
7. Camera-Based Navigation of a Low-Cost Quadrocopter

SCORE the papers from 1 (do not like it) to 4 (love it)

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Please return this sheet by Friday, October 31 to Barbara Frank (building 079, office -1020)